

Research on vibration displacement test method for large-caliber artillery muzzle

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Abstract. In order to solve the problem of muzzle vibration displacement test of large caliber under high elevation, this paper presents a test method by two high-speed photography. The method fully considers the influence of the muzzle torsion on the measurement results, and accurately obtains the three-dimensional vibration displacement of the muzzle of the large caliber artillery. Finally, through the result analysis, the accuracy of the measurement results can reach 0.1 mm, which shows the advantage of the sub-pixel-based high-speed camera processing method in the muzzle vibration displacement test of the conventional artillery. This paper proposes an innovative test method that accurately measures the vibration displacement of the muzzle using a non-contact method.

Keywords: large-caliber, muzzle vibration, high-speed photography, twist, high elevation.

1. Introduction

For large-caliber artillery, the vibration displacement of the muzzle is the main feature affecting the intensity of the artillery [1, 2]. Due to the harsh environment around the muzzle of large caliber artillery, the non-contact method is mainly used for the vibration displacement test of large caliber artillery muzzle. For example, eddy current displacement sensor, photoelectric displacement follower, CCD laser displacement sensor, PSD detector, and high speed photography [3, 4]. A disadvantage of the eddy current displacement sensor is that the measurement range is small. The disadvantage of the photoelectric displacement follower is that it is susceptible to weather and light. And CCD laser displacement sensor and PSD detector are easily affected by smoke and flame when the gun is fired [5, 6].

High speed photography is a non-contact test method widely used in recent years. This method uses a high-speed camera to capture the muzzle motion video when the projectile is fired. The muzzle vibration displacement measurement is then implemented by digital image processing technology. This method has the advantages of high test accuracy and being less susceptible to environmental influences. In this paper, a 155 mm artillery is taken as the research object, and a method for measuring the vibration displacement parameters of large-caliber high-angle artillery muzzle with double high-speed camera is proposed. According to the method, the vibration displacements of the artillery muzzle up and down, left and right, and front and back are obtained at an angle of 45°. The method fully considers the influence of the body tube torsion on the muzzle vibration measurement when the artillery is fired. Through the test verification, the measurement results are in accordance with the vibration law of the artillery muzzle, and the measurement accuracy meets the vibration displacement test requirements of the large-caliber artillery muzzle.

2. The principle of test

When the artillery is fired, the artillery muzzle will have vibration displacements in the up, down, left and right directions [7]. The muzzle vibration displacement is shown in Fig. 1. According to the theory of elastic dynamics [8, 9], during the movement of the projectile in the bore, the barrel generates axial vibration, torsional vibration, and lateral vibration, and the

vibrations in all directions are coupled to each other.

Firstly, a special marker point for image recognition is attached to the outer surface of the muzzle, and then high-speed cameras are used to capture the moving image of the marker point of the muzzle portion during the movement of the projectile. At the end of the shooting, the marker points of the captured muzzle parts are tracked by digital image processing technology to obtain the vibration displacement of the marker points. In the test, the image coordinate axis needs to be aligned with the muzzle vibration displacement direction.

In the vibration displacement test of large-caliber artillery muzzle, the test method based on high-speed camera system has great application potential. As long as the appropriate position, lens, and appropriate tracking algorithm are selected, the muzzle vibration displacement can be accurately obtained.

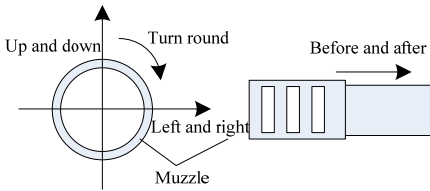


Fig. 1. Muzzle movement diagram

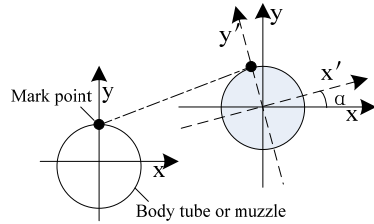


Fig. 2. Marked point motion diagram

2.1. Introduction of test system

Under the high-angle shooting conditions of the large-caliber artillery, two high-speed cameras were placed alternately to measure the vibration displacement of the muzzle. Firstly, the high-speed camera recognition point 1 and the recognition point 2 are pasted along the axis direction of the body tube, as shown in Fig. 3. On the rear end face of the artillery retractor, high-speed camera recognition points 3 and 4 are respectively fixed. Recognition point 8 is attached to the central axis of the upper side surface of the body tube. The distance between the points 1 and 8 to the muzzle is equal, as shown in Fig. 4. Then, a high-speed camera was set up about 15 m from the side of the muzzle. By adjusting the field of view, attitude and focal length of the high-speed camera while observing the high-speed camera display interface, ensure that the body axis is parallel to the x -axis of the high-speed camera. The high-speed camera marks 1 and 2 and the muzzle are clearly imaged in the side high-speed camera image.

Another high-speed camera was set up about 4 m behind the gun. Adjust the field of view, attitude and focal length of the high-speed camera to ensure that the gun barrel is perpendicular to the x -axis of the high-speed camera. The position of the high speed camera is shown in Fig. 5. Since two high-speed cameras are used in the test system, two high-speed cameras can be synchronously triggered with high-precision trigger signals, ensuring that two high-speed cameras have the same time reference.

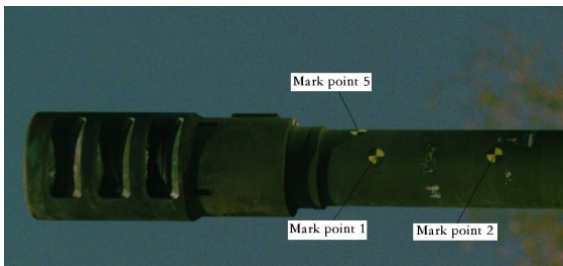


Fig. 3. Marking point on the side of the tube

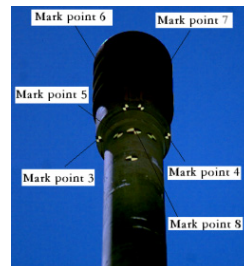


Fig. 4. Marking point on the upper surface of the tube

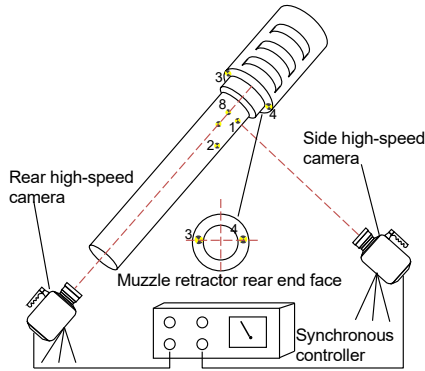


Fig. 5. Muzzle vibration displacement range test schematic

2.2. Calibration of the test system

During the test, neither of the two high-speed cameras was a flat-view target. The presence of the shooting angle has an effect on the measurement results. In this paper, the high-speed camera test system is calibrated by the ruler to eliminate the error caused by the high-speed camera optical axis not perpendicular to the measurement target y -axis. The principle of the system calibration is shown in Fig. 6. If the optical axis of the high-speed camera is perpendicular to the plane of the target, the number of pixels occupied by the scale L is m , and the object moves b pixels. Then there is: $s_1 = \frac{L}{m} \times b = \frac{P \cos \alpha}{m} \times b$, $s_2 = \frac{s_1}{\cos \alpha} = \frac{P}{m} \times b$.

When the angle between the imaging surface of the high-speed camera and the plane being measured is α . First, the camera is calibrated by selecting a scale that is consistent with the measurement direction on the measurement plane, that is, the correspondence between the distance and the pixel is obtained. Then, using the camera after calibration, the actual displacement s_2 of the object can be obtained.

The entire calibration process is done automatically by the image processing system. The calibration result can be obtained by measuring the distance between the two marks in the direction in advance and taking the image of the mark by a high-speed camera.

Certain principles need to be followed during the calibration process. The scale should be fixed on the plane of the target to be measured, and the direction of the scale should be consistent with the direction of displacement of the target.

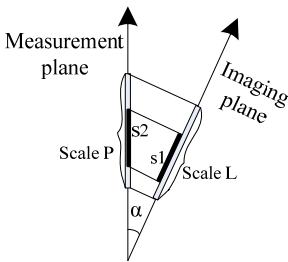


Fig. 6. System calibration diagram

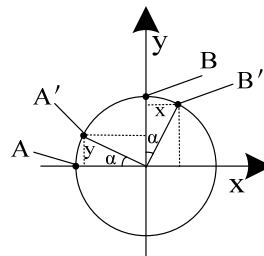


Fig. 7. Schematic diagram of the muzzle twist angle

2.3. Test result processing

Observed from the perspective of the high-speed side view of the front side, the torsional displacement of the muzzle does not affect the displacement of the marker points 1 and 2 in the recoil direction.

If the recoil displacements of points 1 and 2 are x_{r1} and x_{r2} , the vibration displacement in the

front and rear direction of the muzzle is:

$$X_{recoil} = (x_{r1} + x_{r2})/2. \quad (1)$$

The displacement of the marker point 1 in the y direction is composed of the upper and lower vibration displacement and the torsional displacement of the muzzle. Then there is:

$$y_p = Y_u + y_{t1}, \quad (2)$$

where Y_u is the vibration displacement of the muzzle in the up and down direction, and y_{t1} is the displacement component of the marker point 1 in the y direction due to the torsional action.

The x -direction displacement of the marker point 3 is composed of the vibration displacement in the left-right direction of the muzzle and the displacement due to the torsion, that is, $x_{M3} = X_L + x_{t3}$.

Similarly, according to Fig. 5, $x_{M4} = X_L - x_{t4}$, $x_{M8} = X_L + x_{t8}$.

X_L is the vibration displacement of the muzzle in the left and right direction, and x_{t3} is the displacement component of the marker point 3 due to the torsion in the x direction. x_{t4} , x_{t5} and x_{t3} have similar meanings.

If the muzzle is twisted to a uniform twist, there is $x_{t3} = x_{t4}$, then there is:

$$X_L = (x_{M3} + x_{M4})/2, \quad (3)$$

$$x_{t3} = (x_{M3} - x_{M4})/2, \quad (4)$$

$$x_{t8} = x_{M8} - X_L = x_{M8} - (x_{M3} + x_{M4})/2. \quad (5)$$

Assuming that the muzzle is evenly twisted, the torsion angle is α , and the muzzle torsion is shown in Fig. 7.

As can be seen from Fig. 7, if the marker point A is on the center line of the front side of the body tube, the marker point B is on the center line of the upper surface of the body tube. Due to the muzzle twisting effect, the marker point A is twisted to the marker point A' , and the marker point B is reversed to the marker point B' . Then, there are $x_A = y_B$, $y_A = x_B$, where x_A is the displacement component of the marker point A due to the torsion in the x direction, and y_A is the displacement component of the marker point A generated by the torsion in the y direction. And x_B , y_B are similar.

In the actual measurement, the marker points 1 and 8 conform to the characteristics of the marker points A and B in Fig. 7.

So, there is:

$$Y_u = y_p - x_{t8} = y_p - \left(x_{M8} - \frac{x_{M3} + x_{M4}}{2} \right). \quad (6)$$

According to the Eqs. (1), (3), (6), the three-dimensional vibration displacement of the artillery muzzle can be obtained. However, this method requires precise sticking of the marker points (error less than 0.5 mm) and accurate measurement of the distance scale (error less than 0.5 mm).

3. Application in vibration displacement measurement of a 155 mm artillery muzzle

Taking a 155 mm gun as the test object, the muzzle vibration displacement was tested by this method under the 45° angle of shooting condition. During the test, the high-speed camera frame rate is set to 10000 f/s, the pixel selection is 1280×800, and the 200 mm fixed-focus lens is used. When analyzing the sequence of images taken by a high-speed camera, the distance scale measured in advance is used as an input. Then, the feature points and marker points in the image are automatically tracked, and the displacements in the x and y directions are calculated. The test

results are shown in Figs. 8-11.

In Figs. 8-11, the end point of the curve is the moment when the projectile exits the muzzle. By analyzing the vibration displacement curve of the muzzle, it can be obtained that during the movement of the projectile, the vibration displacement of the artillery muzzle reaches the maximum at the muzzle exit time, which is 101 mm. The vibration displacement of the artillery muzzle in the up and down direction has always been negative, indicating that the muzzle has been moving downward from the start of the projectile, and the projectile reaches the maximum at the muzzle moment, about 1.5 mm. The vibration displacement curve of the artillery muzzle in the left and right direction indicates that the muzzle is always biased to the left, and the moment of the muzzle reaches the maximum, about 2.4 mm. The torsion displacement of the muzzle is also the largest at the moment when the projectile exits the muzzle, and it is counterclockwise, about 1.4 mm. The curve rule is consistent with the vibration law of the artillery muzzle.

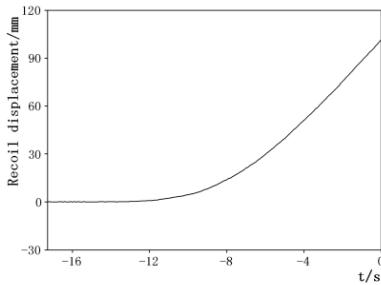


Fig. 8. Recoil displacement

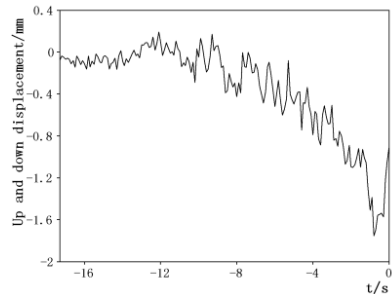


Fig. 9. Movement displacement of the muzzle in the up and down direction

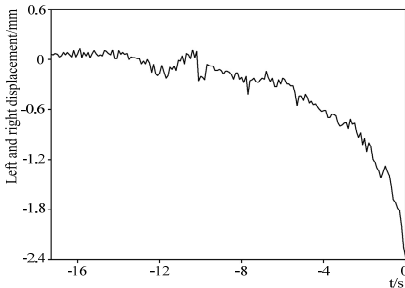


Fig. 10. Displacement in the left and right direction

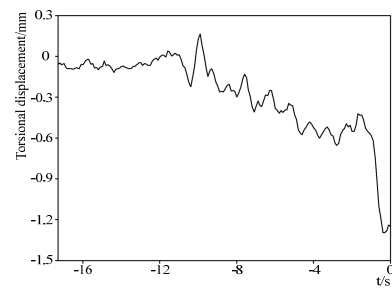


Fig. 11. Muzzle torsional displacement

4. Measurement uncertainty analysis

Since the muzzle vibration displacement is directly measured by image processing, Therefore, the main component (class B evaluation) of the standard uncertainty $u(L)$ of its single measurement (left and right muzzle vibration displacement) is:

(1) The maximum background noise of the displacement curve obtained after image processing is ± 0.025 mm, normal distribution, then the uncertainty introduced by this term is: $\mu_1 = 0.025/2 = 0.0125$ mm;

(2) Subpixel tracking error is 20 %, normal distribution, take the muzzle vibration to 0.8 mm, then the uncertainty introduced by this term is: $\mu_2 = 0.2 \times 0.8 \div (2 \times 2) = 0.04$ mm;

(3) The maximum error of ruler is 0.5mm, uniform distribution, the ruler spacing is 120 mm, take the muzzle vibration to 0.8 mm, then the uncertainty introduced by this term is: $\mu_3 = 0.5 \times 0.8 \div (120 \times 2 \times 31/2) = 0.001$ mm;

(4) The error of the local deformation of the muzzle is estimated to be 0.02 mm, normal

distribution, then the uncertainty introduced by this term is: $\mu_4 = 0.02 \div (2 \times 2) = 0.005$ mm;

(5) The image of the camera barrel at the back is not perpendicular to the x-axis, the maximum error is 0.02 mm, normal distribution, then the uncertainty introduced by this term is: $\mu_5 = 0.02 \div (2 \times 2) = 0.005$ mm;

(6) The maximum error of the marker point is 1 pixel (about 0.5 mm), resulting in a single mark point torsion measurement error of 0.05 mm, vibration displacement test error is 0.1 mm, normal distribution, then the uncertainty introduced by this term is: $\mu_6 = 0.1 \div (2 \times 2) = 0.025$ mm;

(7) The uncertainty introduced by high-speed camera calibration is 2.2 %, take the muzzle vibration to 0.8 mm, then the uncertainty introduced by this term is: $\mu_7 = 0.022 \times 0.8 \div 2 = 0.0088$ mm;

Then the total standard measurement uncertainty is: $\mu_c(L) = \mu_{12} + \mu_{22} + \mu_{32} + \mu_{42} + \mu_{52} + \mu_{62} + \mu_{72}/2 = 0.05$ mm, extended uncertainty is: take a confidence level of 95 %, $k = 2$, the resulting extended uncertainty is:

$$U_p(L) = k \times \mu_c(L) = 0.1 \text{ mm.} \quad (7)$$

5. Conclusions

Through the application of vibration displacement measurement method of high elevation muzzle of large-caliber gun, the vibration displacement of the 155 mm gun at the front and rear, up and down and left and right sides of the artillery muzzle at 45° angle is obtained. The uncertainty of the measurement result is about 0.1 mm, and the measurement accuracy fully meets the requirements of the vibration displacement of the muzzle to the measurement system.

As a non-contact test method, it can eliminate the impact of the tube twist on the test results and obtain a more accurate three-dimensional displacement of the muzzle. The test system is not affected by the muzzle shock wave and the vibration of the artillery, and is fully applicable to the three-dimensional vibration displacement test of the large-caliber artillery muzzle. In the small vibration displacement test of weapons and equipment, the test method also has certain advantages and potentials.

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